

Áramerősség

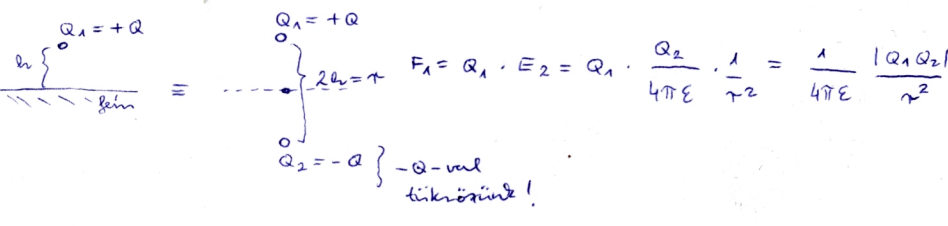
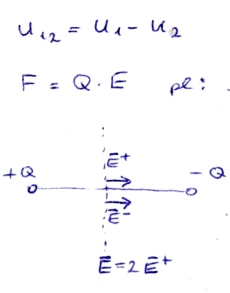
$R_0 = \frac{l}{\sigma \cdot A}$
 $R_N = \frac{l}{\sigma k S}$
 $f_{Cu}^{[m]} = \frac{6.67 \cdot 10^{-2}}{\sqrt{f Hz}}$
 $R_{max N} = R_{BN} + R_{KN}$
 $R' = R/l$

$\mu = \mu_r \mu_0$
 $\mu_0 = 4\pi \cdot 10^{-7} \frac{Vs}{Am}$
 $\epsilon = \epsilon_r \epsilon_0$
 $\epsilon_0 = 8.85 \cdot 10^{-12} \frac{As}{Vm}$
 $\epsilon_0 = \frac{1}{\mu_0 c^2}$; $c = 3 \cdot 10^8 \frac{m}{s}$
 $\sigma = \frac{1}{Re\{z\}} = \frac{1}{\alpha}$
 $\omega = 2\pi f$; $T = c/f$

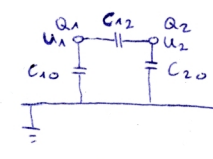
Elektrosztatika

MAX. IV: $div \vec{D} = S$
 $\oint_a \vec{D} da = \int_V S dv$

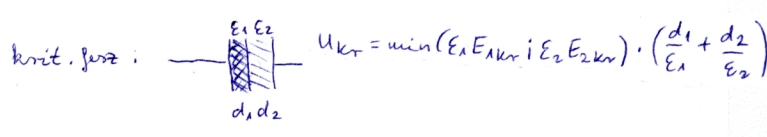
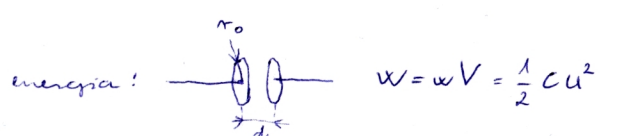
$SV = Qi$; $A = 4\pi r^2$
 pont/gömb $\vec{D} = \epsilon \vec{E}$
 $\epsilon E \cdot 4\pi r^2 = Q \rightarrow E = \frac{Q}{4\pi \epsilon} \cdot \frac{1}{r^2}$
 $\vec{E} = -grad U$
 $U = -\frac{Q}{4\pi \epsilon} \int \frac{1}{r^2} dr = \frac{Q}{4\pi \epsilon} \cdot \frac{1}{r}$
 $\int \frac{1}{r^2} = -\frac{1}{r}$
 vonal/heng. $SV = q \cdot l$; $A = 2\pi r \cdot l$
 $\epsilon E \cdot 2\pi r \cdot l = ql \rightarrow E = \frac{q}{2\pi \epsilon} \cdot \frac{1}{r}$
 $U = -\frac{q}{2\pi \epsilon} \int \frac{1}{r} dr = -\frac{q}{2\pi \epsilon} \cdot \ln(r)$
 $\int \frac{1}{r} = \ln(r)$



kapacitás C = Q/U



részkapac: $Q_1 = C_{10} U_1 + C_{12} (U_1 - U_2)$
 $(Q = CU)$ $Q_2 = C_{20} U_2 + C_{12} (U_2 - U_1)$
 kapac: $\begin{bmatrix} Q_1 \\ Q_2 \end{bmatrix} = \begin{bmatrix} C_{11} & C_{12} \\ C_{12} & C_{22} \end{bmatrix} \begin{bmatrix} U_1 \\ U_2 \end{bmatrix}$



Térbeli áramlás analógia:

el. áramlás	D	E	E	Q	$D [\frac{As}{m^2}]$; $E [\frac{Vs}{m}]$; $E [\frac{V}{m}]$; $Q [C = As]$
stac. ár.	$\vec{\nabla}$	$\vec{\nabla}$	$\vec{\nabla}$	I	$\vec{\nabla} [\frac{A}{m^2}]$; $\vec{\nabla} [\frac{S}{m} = \frac{A}{Vm}]$; $E [\frac{V}{m}]$; $I [A]$

példa: pont/gömb: $E = \frac{1}{4\pi \epsilon} \cdot \frac{1}{r^2} \rightarrow U = \frac{1}{4\pi \epsilon} \cdot \frac{1}{r} \rightarrow P = U \cdot I = 4\pi \epsilon \cdot r \cdot U^2$; $R = \frac{U}{I} = \frac{1}{4\pi \sigma} \cdot \frac{1}{r}$

$I = \vec{\nabla} \cdot \vec{A}$

$|\vec{\nabla}| = |\vec{I}|/A$ pe.
 $\vec{G} = 0$
 $\vec{G} [S/m]$
 $\vec{v} [m/s]$
 $I = [A]$
 $(\vec{v} \cdot \vec{e}_r)$
 $I' = +I$ } nem -I-vel $tiközönít!$
 $I' = +I$ } $|\vec{\nabla}| = |\vec{\nabla}'|$
 $\vec{\nabla}' = \frac{1}{4\pi (r^2 + x^2)} \cdot \frac{x}{\sqrt{r^2 + x^2}} \cdot 2 \cdot \vec{e}_x [\frac{A}{m^2}]$

Mágneses tér

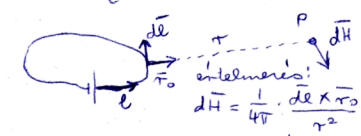
MAXI. $rot \vec{H} = \vec{\nabla} \times \vec{J} + \frac{\partial \vec{D}}{\partial t}$
 $\oint \vec{H} dl = \int \vec{J} da = I$

egyfel: $B = \mu H$
 $Hl = N \cdot I$
 $N\Phi = L \cdot I$
 $\Phi = B \cdot A$
 $L = \frac{N\Phi}{I} = \frac{NBA}{I} = \frac{N\mu HA}{I} = \frac{N\mu HA}{HL} = \frac{N^2 \mu A}{L} = L_{ön}$

(fluxus: $\Phi = \int B da = \oint \vec{A} d\vec{l}$ [$V_s = W_b$])
 \vec{A} : mágneses vektor pot.

Biot-Savart

$\vec{H} = \frac{1}{4\pi} \oint \frac{d\vec{l} \times \vec{r}_0}{r^2}$



∞ vektörre: (2 párhuzamosos) $\vec{H} = \frac{1}{2\pi} \cdot \frac{1}{r} (H\vec{e}_\perp + h\vec{e}_\parallel)$
 $H\vec{e}_\perp + H\vec{e}_\parallel = N \cdot I$
 $H = n \cdot \frac{1}{4\pi r} \cdot [\sin \beta]$

egyenes vezeték:
 $H_v l + H_e l = N \cdot I$; $H_v \cdot \mu r = H_e$
 $w = \frac{1}{2} BH = \frac{1}{2} \mu H^2 [\frac{J}{m^3}]$

de valójában az, exponenciál határolt adja meg

MAXWELL - EGYENLETEK

I. Általános egyenlet: to.

$$\text{rot } \vec{H} = \vec{J} + \frac{\partial \vec{D}}{\partial t}$$

II. Faraday-féle indukció to.

$$\text{rot } \vec{E} = - \frac{\partial \vec{B}}{\partial t}$$

III. Mágneses Gauss to.

$$\text{div } \vec{B} = 0$$

IV. Elektrosztatikai Gauss to.

$$\text{div } \vec{D} = \rho$$

V. Körhajléltató törvények

Mágneses indukció vektora

$$\vec{B} = \mu \vec{H}$$

Elektromos eltolódás vektora

$$\vec{D} = \epsilon \vec{E}$$

Differenciális Ohm to.

$$\vec{J} = \sigma \cdot \vec{E}$$

VI. Energia

$$w = \frac{1}{2} \vec{H} \cdot \vec{B} + \frac{1}{2} \vec{E} \cdot \vec{D}$$

Az elektrodinamika jelöltése: Isőben állandó EM tér:

Magnetostatika

H	E
B	D
μ	ϵ

I. $\text{rot } \vec{H} = 0$

III. $\text{div } \vec{B} = 0$

V. $\vec{B} = \mu \cdot \vec{H}$

Stac. mágn. tér

I. $\text{rot } \vec{H} = \vec{J}$

III. $\text{div } \vec{B} = 0$

V. $\vec{B} = \mu \cdot \vec{H}$

Elektrosztatika

II. $\text{rot } \vec{E} = 0$

IV. $\text{div } \vec{D} = \rho$

V. $\vec{D} = \epsilon \vec{E}$

Stac. ár. tér

II. $\text{rot } \vec{E} = 0$

IV. $\text{div } \vec{E} = 0$

V. $\vec{E} = \sigma \cdot \vec{E}$

EGYÉB GYÖNYÖRŰSÉGEK

differenciális alakt \rightarrow integrális alakt

$\text{rot } \vec{X} \rightarrow \oint \vec{X} \cdot d\vec{l}$

$\text{div } \vec{X} \rightarrow \oint \vec{X} \cdot d\vec{a}$

peremfeltételek:

el. stat	$D = \epsilon E$	
stac. ár	$J = \sigma E$	pl. $E_{1t} = E_{2t}$
mágneses	$B = \mu H$	$D_{1n} = D_{2n}$

1-2 határon: \downarrow norm. \downarrow tang.

\uparrow 1. körg \uparrow 2. körg

Φ skalarpotra a norm. Dirichlet peremfeltétel: $n \times \nabla \Phi = 0$

tétel
 négyzetöltéseloszlás lefelől
 elektromos tér \Leftrightarrow ha $\text{rot } \vec{E} = 0$
 (cőtvénymentes)

MATEK

$$\text{grad } \phi = \frac{\partial \phi}{\partial x} \vec{e}_x + \frac{\partial \phi}{\partial y} \vec{e}_y + \frac{\partial \phi}{\partial z} \vec{e}_z$$

$$\text{div } \vec{v} = \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z}$$

$$\vec{B} = \text{rot } \vec{A} = \begin{vmatrix} \vec{e}_x & \vec{e}_y & \vec{e}_z \\ \partial/\partial x & \partial/\partial y & \partial/\partial z \\ A_x & A_y & A_z \end{vmatrix}$$

ahol \vec{A} : vektorpotencial
 (U_n : skalárpot.)

$$\Delta U = \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) \cdot U \text{ (Laplace-operátor)}$$

integrálok:

$$\int \frac{1}{r^2} dr = -\frac{1}{r} \quad \int \frac{1}{r} dr = \ln(r)$$

MAGIC FORMULA a funkció

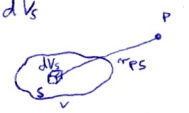
∞ vez: $\Phi_{AB} = \frac{q}{4\pi \epsilon_0} \left(\ln \frac{1}{r_{A\text{közp.}}} - \ln \frac{1}{r_{B\text{közp.}}} \right)$

gömb: $\Phi_{AB} = \frac{q}{4\pi \epsilon_0} \left(\frac{1}{A} - \frac{1}{B} \right)$

Poisson

skalárs P. + m.o.

$$\Delta U = -\frac{\rho}{\epsilon} \Rightarrow \Phi(P) = \frac{1}{4\pi \epsilon} \int \frac{\rho(s)}{r_{ps}} dV_s$$



vektorális P. + m.o.

$$\Delta \vec{A} = -\mu \vec{J} \Rightarrow \vec{A}(P) = \frac{\mu}{4\pi} \int \frac{\vec{J}(s)}{r_{ps}} dV_s$$

