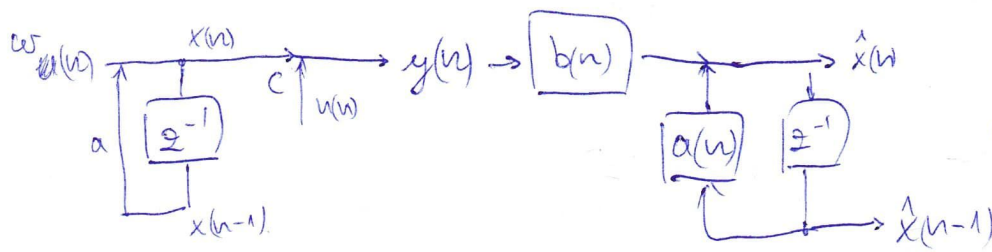


## 2.2H megoldás

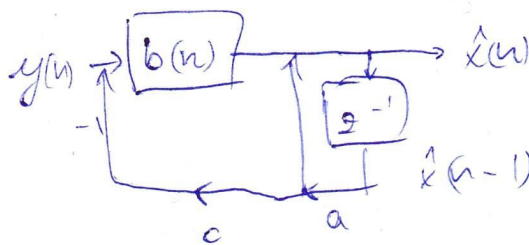
Méréselm.  
13.E  
36/  
2018.05.15.

$$\textcircled{1} \quad x(n) = a x(n-1) + w(n)$$

$$y(n) = c x(n) + u(n)$$



$$a(n) = \frac{a}{1 - b(n)}$$



rendszer zaj:  $E[w(n)] = 0$ ,  $\sigma_w^2$ ,  $E[w(n)w^T(m)] = Q(n)$

megfigyelési zaj:  $E[u(n)] = 0$ ,  $\sigma_u^2$ ,  $E[u(n)u^T(m)] = R(n)$

$$e(n) = x(n) - \hat{x}(n) \quad E[(x(n) - \hat{x}(n))^2] \rightarrow \text{min.}$$

$$\hat{x}(n) = a \hat{x}(n-1) + b(n) y(n) \quad \hookrightarrow \frac{\partial}{\partial a(n)} = -2 E[e(n) \hat{x}(n-1)] = 0$$

$$\frac{\partial}{\partial b(n)} = -2 E[e(n) y(n)] = 0$$

$$\textcircled{2} \quad \hat{x}(n) = \frac{1}{N} \sum_{\ell=n-N}^{n-1} y(\ell) \quad \hat{x}(n+1) = \frac{1}{N} \sum_{\ell=n-N+1}^{n} y(\ell) = \hat{x}(n) + \frac{1}{N} [y(n) - y(n-N)]$$

$$z \hat{x}(z) = \hat{x}(z) + \frac{1}{N} (1 - z^{-N}) Y(z)$$

$$H(z) = \frac{\hat{x}(z)}{Y(z)} = \frac{z^{-1}}{N} \frac{1 - z^{-N}}{1 - z^{-1}}$$

$$\left| H(z) \Big|_{z=e^{j\omega T}} \right| = \frac{e^{-j\omega T}}{N} \cdot \frac{1 - e^{-j\omega NT}}{1 - e^{-j\omega T}} = \frac{e^{-j\omega T} e^{-j\frac{N}{2}\omega T} (e^{j\frac{N}{2}\omega T} - e^{-j\frac{N}{2}\omega T})}{N e^{-j\frac{N}{2}\omega T} (e^{j\frac{N}{2}\omega T} - e^{-j\frac{N}{2}\omega T})} =$$

$$= \frac{e^{-j\frac{N+1}{2}\omega T} \sin\left(\frac{N}{2}\omega T\right)}{N \sin\left(\frac{1}{2}\omega T\right)}$$

$$|H(e^{j\omega T})| = \frac{1}{N} \left| \frac{\sin\left(\frac{N}{2}\omega T\right)}{\sin\left(\frac{1}{2}\omega T\right)} \right| = \frac{1}{N} \left| \frac{\sin\frac{3\pi}{2}}{\sin\frac{3\pi}{20}} \right| \approx 0,22$$

③  $1 + \sin \omega t + \cos \omega t$   $N=4; \frac{2\pi}{N}$

$$1 + \sin \frac{2\pi}{4} n + \cos \frac{2\pi}{4} n$$

$$y = \begin{bmatrix} 2 \\ 2 \\ 0 \\ 0 \end{bmatrix} \quad F_y = \frac{1}{4} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & j & -1 & j \\ 1 & -1 & 1 & -1 \\ 1 & -j & -1 & -j \end{bmatrix} \cdot \begin{bmatrix} 2 \\ 2 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 0,5 - 0,5j \\ 0 \\ 0,5 + 0,5j \end{bmatrix}$$

$$\omega y = \frac{1}{4} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & -1 & -1 \\ 1 & 1 & -1 & 1 \\ 1 & -1 & 1 & -1 \end{bmatrix} \begin{bmatrix} 2 \\ 2 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \end{bmatrix}$$

④  $(1 - z^{-N}) \left( \frac{z_m z^{-1}}{1 - z_m z^{-1}} + \frac{z_m^{-1} z^{-1}}{1 - z_m^{-1} z^{-1}} \right)$

$$\frac{(1 - z^{-N}) z_m z^{-1}}{1 - z_m z^{-1}} = z_m z^{-1} + (z_m z^{-1})^2 + (z_m z^{-1})^3 + \dots + (z_m z^{-1})^N + (z_m z^{-1})^{N+1} + \dots - (z_m z^{-1}) z^{-N}$$

$$\downarrow$$

$$z_m$$

$\downarrow$   
 $z_m^N z_m$   
 $= 1$ , mert  $N$ -edik egyenlőség

$$H(z) = a_1 z^{-1} + a_2 z^{-2} + \dots + a_N z^{-N}$$

$$a_\ell = z_m^\ell = e^{j \frac{2\pi}{N} m \ell}$$

$$a_\ell = z_m^\ell + z_m^{-\ell} = e^{j \frac{2\pi}{N} m \ell} + e^{-j \frac{2\pi}{N} m \ell} = 2 \cos\left(\frac{2\pi}{N} m \ell\right)$$

$$y(0) = 0$$

$$y(1) = 2 \cos\left(\frac{2\pi}{N} m\right)$$

$$y(2) = 2 \cos\left(\frac{2\pi}{N} m \cdot 2\right) \dots$$

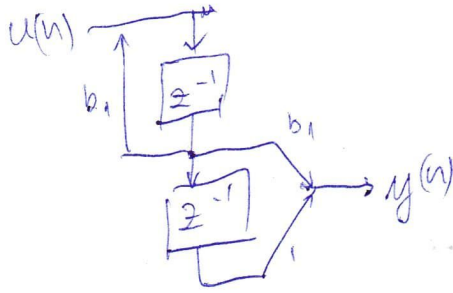
$$N=5 \Rightarrow \omega = \frac{2\pi}{5} \cdot 2 \cdot m$$

$$y(N) = 2 \cos\left(\frac{2\pi}{N} n N\right) = 2$$

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⑤  $\frac{z^{-1}z^{-1} + ab_1}{1 + b_1z^{-1}}$

Mindegyik szűrő:  $|H(z)| = 1$  ← Egyjegyűtől származik



$$\begin{aligned} z^{-1} \frac{z^{-1} + b_1}{1 + b_1z^{-1}} &= \frac{z + b_1}{1 + b_1z} \\ &= \frac{1 + b_1(z^{-1} + z) + b_1^2}{1 + b_1(z^{-1} + z) + b_1^2} = 1 \quad \checkmark \end{aligned}$$

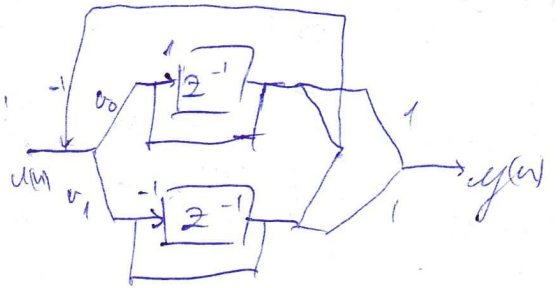
$$z_0 = 1 \quad H_0(z) = \frac{r_0 z^{-1}}{1 - z^{-1}} \quad \omega_0 = 1$$

$$z_1 = -1 \quad H_1(z) = \frac{r_1 z^{-1}}{1 + z^{-1}} \quad \omega_1 = 1$$

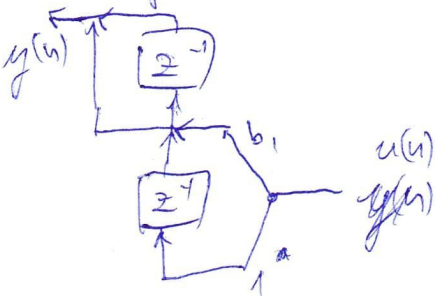
$$\frac{H_0(z)\omega_0 + H_1(z)\omega_1}{1 + H_0(z)\omega_0 + H_1(z)\omega_1} = \frac{\frac{r_0 z^{-1}}{1 - z^{-1}} + \frac{r_1 z^{-1}}{1 + z^{-1}}}{1 + \frac{r_0 z^{-1}}{1 - z^{-1}} + \frac{r_1 z^{-1}}{1 + z^{-1}}} = \frac{r_0 z^{-1} + r_1 z^{-2} - r_1 z^{-1} + r_0 z^{-2}}{1 - z^{-2} + r_0 z^{-1} + r_1 z^{-2} - r_1 z^{-1} + r_0 z^{-2}}$$

$$= \frac{(r_0 - r_1)z^{-1} + (r_0 + r_1)z^{-2}}{1 + (r_0 - r_1)z^{-1} + (r_0 + r_1)z^{-2}} = \frac{b_1 z^{-1} + z^{-2}}{1 + b_1 z^{-1}}$$

$$\left. \begin{aligned} r_0 - r_1 &= b_1 \\ r_0 + r_1 &= 1 \\ r_0 - r_1 &= b_1 \\ r_0 + r_1 - 1 &= 0 \end{aligned} \right\} \Rightarrow r_0 = \frac{1 + b_1}{2} \quad r_1 = \frac{1 - b_1}{2}$$



Transzponált struktúra:



⑥  $\left| \frac{a + bj}{1 + abj} \right| \leq 1$

$$a^2 + b^2 \leq (1 + a)^2 + b^2$$

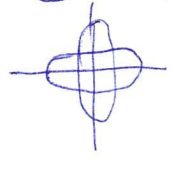
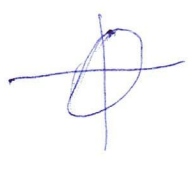
$$0 \leq 1 + 2a$$

$$a \geq -\frac{1}{2}$$

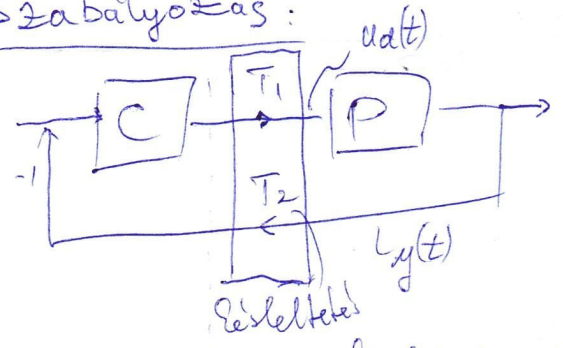


$$H(z) = z^{-1} \frac{z^{-1} + b_1}{1 + b_1 z^{-1}}$$

$$P_D = \begin{bmatrix} 1 & b_1 \\ b_1 & 1 \end{bmatrix} \quad P_R = \begin{bmatrix} \frac{2}{1+b_1} & 0 \\ 0 & \frac{2}{1+b_1} \end{bmatrix}$$

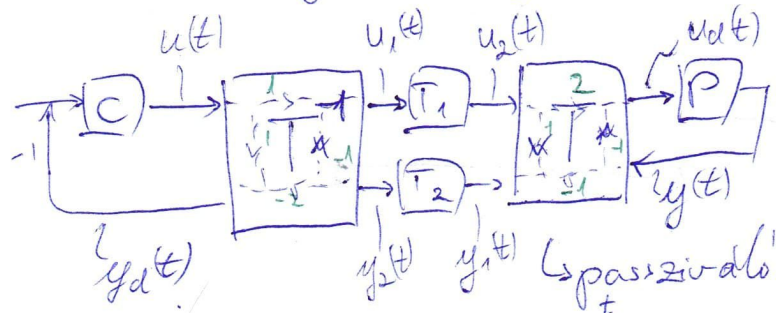


Szabályozás:



→ a hálózatot dissipatívul tekinthetjük

P dissipatív:  $\int_0^t P_{in} dt = \int_0^t u_d(t) y_d(t) dt \geq 0$



↳ passzív dő transformáció

Hálózaton belüli energia:  $U_N = \int_0^t u_1^T(\tau) y_1^T(\tau) + y_1^T(\tau) y_1(\tau) - u_2^T(\tau) u_2(\tau) - y_2^T(\tau) y_2(\tau) dt$

$$u_2(t) = u_1(t - T_1)$$

$$y_2(t) = y_1(t - T_2)$$

$$= \int_{t-T_1}^t u_1^T(\tau) u_1(\tau) dt + \int_{t-T_2}^t y_1^T(\tau) y_1(\tau) dt \geq 0$$

$$\int_0^t u_1^T(\tau) u_1(\tau) - y_2^T(\tau) y_2(\tau) dt \geq \int_0^t u_2^T(\tau) u_2(\tau) - y_1^T(\tau) y_1(\tau) dt$$

$$\begin{bmatrix} u_d(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} u_2(t) \\ y_1(t) \end{bmatrix} = \begin{bmatrix} u_2(t) + y_1(t) \\ u_2(t) - y_1(t) \end{bmatrix} \cdot \begin{bmatrix} u_d(t) \\ y_1(t) \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} u_2(t) \\ y_1(t) \end{bmatrix}$$

$$\begin{bmatrix} u(t) \\ y_2(t) \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} u_1(t) \\ y_2(t) \end{bmatrix} = \begin{bmatrix} u_1(t) + y_2(t) \\ u_1(t) - y_2(t) \end{bmatrix}; \begin{bmatrix} u_1(t) \\ y_d(t) \end{bmatrix} = \begin{bmatrix} 1 & -1 \\ 1 & -2 \end{bmatrix} \begin{bmatrix} u(t) \\ y_2(t) \end{bmatrix}$$

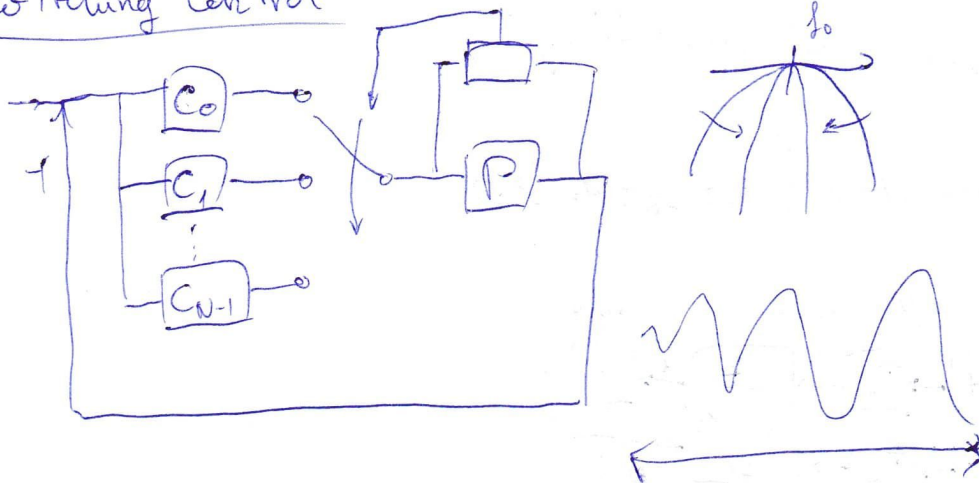
$$P(s) \neq P_1(s) = 1 - 2 \frac{P(s)}{1+P(s)} = \frac{1-P(s)}{1+P(s)}$$

$$K(s) = e^{-sT_1} + e^{-sT_2}$$

$$P_2(s) = 1 - 2 \cdot \frac{K(s) P_1(s)}{1 + K(s) P_1(s)} = \frac{1 - K(s) P_1(s)}{1 + K(s) P_1(s)} = \frac{1 + P(s) - K(s)(1 - P(s))}{1 + P(s) + K(s)(1 - P(s))} =$$

$$= \frac{1 - K(s) + P(s)(1 + K(s))}{1 + K(s) + P(s)(1 - K(s))}$$

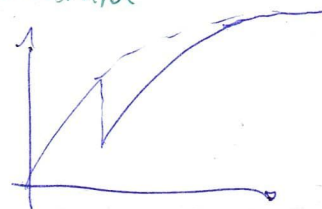
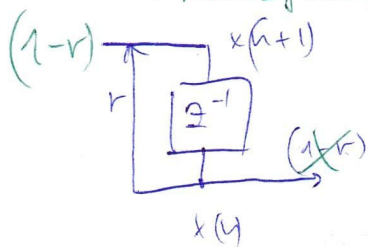
Switching control



$$H(z) = \frac{(1-r)z^{-1}}{1-rz^{-1}} \quad H(z) \Big|_{z=1} = 1$$

$$H(z) \Big|_{z=-1} = \frac{-r(1-r)}{1+r}$$

transzpondt struktúra



$$x(0) = 0$$

$$x(1) = 1$$

$$x(2) = 1+r$$

$$x(n) = 1 + r + r^2 + \dots + r^{n-1} \rightarrow \frac{1}{1-r}$$