

Általános összefüggések

$$|U_V| = \sqrt{3} |U_F| = |U|$$

$$|I_V| = |I_F| = I = \sqrt{3} |I_A|$$

$$|Z^Y| = \frac{|U_F|}{|I|}$$

$$|Z^A| = 3 |Z^Y|$$

$$S_{3\phi} = S = 3 |U_F| |I_F| = \sqrt{3} U I$$

$$P_{3\phi} = P = \sqrt{3} U I \cos \varphi \quad Q = -\sqrt{3} |U| |I| \sin \varphi$$

transzformátor:

$$\varepsilon^{\%} = \frac{U_{rZ}^N}{U_{fN}^N} 100$$

$$U_{rZ} = Z^N I_u^N$$

$$Z^N = \frac{\varepsilon}{100} \frac{U_u^N}{S_u}$$

$$S_{rZ} = \frac{\sqrt{3} U_u I_u}{\varepsilon / 100}$$

generátor:

$$X_q^2 = \frac{X^{\%}}{100} \frac{U_u^2}{S_u}$$

$$U_k \approx \frac{U_u}{\sqrt{3}}$$

$$\cos \varphi \Rightarrow \varphi$$

$$S_u = \sqrt{3} U_u I_u$$

nagy hálózati:

$$S_Z = \sqrt{3} U_u I_u$$

$$X^H = \frac{U_u^2}{S_Z}$$

∞ hálózati:

$$S_Z = \infty$$

$$X^H = \phi$$

$$U = U_u$$

tauvezetékek:

$$D = rL$$

$$X_L = X_L l$$

$$X_C = \frac{x_C}{l}$$

foqyasatd:

$$S_u = \sqrt{3} U_u I_u$$

• Z tartd:

$$Z = \frac{U_u^2}{S_u} (\cos \varphi \overset{\text{ind.}}{\underset{\text{kap.}}{\mp}} \sin \varphi)$$

• I tartd:

$$I_I = \frac{S_u}{\sqrt{3} U_u} (\cos \varphi \overset{\text{ind.}}{\underset{\text{kap.}}{\mp}} \sin \varphi)$$

Szimmetrikus öszetevűkre való bontás:

$$\begin{aligned} \bar{I}_f &= \bar{T} \bar{I}_s & \bar{I}_s &= \bar{T}^{-1} \bar{I}_f & U_s &= \begin{bmatrix} U_0 \\ U_1 \\ U_2 \end{bmatrix} & U_f &= \begin{bmatrix} U_a \\ U_b \\ U_c \end{bmatrix} \\ \bar{U}_f &= \bar{T} \bar{U}_s & \bar{U}_s &= \bar{T}^{-1} \bar{U}_f \end{aligned}$$

$$\bar{T} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & a^2 & a \\ 1 & a & a^2 \end{bmatrix} \quad \bar{T}^{-1} = \frac{1}{3} \begin{bmatrix} 1 & 1 & 1 \\ 1 & a & a^2 \\ 1 & a^2 & a \end{bmatrix} \quad I_s = \begin{bmatrix} I_0 \\ I_1 \\ I_2 \end{bmatrix} \quad I_f = \begin{bmatrix} I_a \\ I_b \\ I_c \end{bmatrix}$$

$$I_a = I^0, I_b = I a^2, I_c = I a$$

$$a = 1 e^{j120^\circ}$$

$$1 + a + a^2 = 0 \quad a^3 = 1 \quad a^4 = a$$

$$\bar{U}_f = \bar{Z}_f \bar{I}_f$$

$$\bar{Z}_f = \begin{bmatrix} Z_{aa} & Z_{ab} & Z_{ac} \\ Z_{ba} & Z_{bb} & Z_{bc} \\ Z_{ca} & Z_{cb} & Z_{cc} \end{bmatrix}$$

$$\bar{U}_s = \bar{Z}_s \bar{I}_s$$

$$\bar{Z}_s = \begin{bmatrix} Z_{00} & Z_{01} & Z_{02} \\ Z_{10} & Z_{11} & Z_{12} \\ Z_{20} & Z_{21} & Z_{22} \end{bmatrix}$$

$$\bar{I}_s = \bar{T}^{-1} \bar{Z}_f \bar{T} \bar{I}_s$$

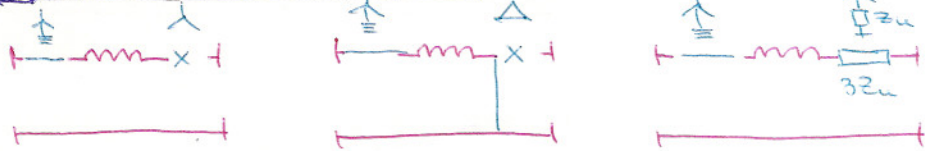
$$\bar{Z}_f = \begin{bmatrix} Z_{00} & Z_{01} & Z_{02} \\ Z_{10} & Z_{11} & Z_{12} \\ Z_{20} & Z_{21} & Z_{22} \end{bmatrix}$$

$$\bar{Z}_s = \begin{bmatrix} Z_0 + Z_1 + Z_2 & 0 & 0 \\ 0 & Z_0 + a^2 Z_1 + a Z_2 & 0 \\ 0 & 0 & Z_0 + a Z_1 + a^2 Z_2 \end{bmatrix}$$

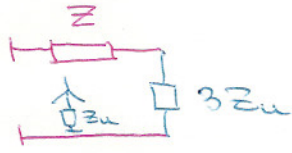
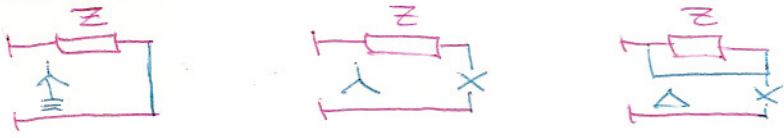
$Z_0 \quad Z_1 \quad Z_2$

• ha $Z_{01} = Z_{10} = Z_{20} = Z_{02} = Z_{12} = Z_{21}$
 $Z_0 = Z_0 + 2Z_{12}$
 $Z_1 = Z_2 = Z_0 - Z_{12}$

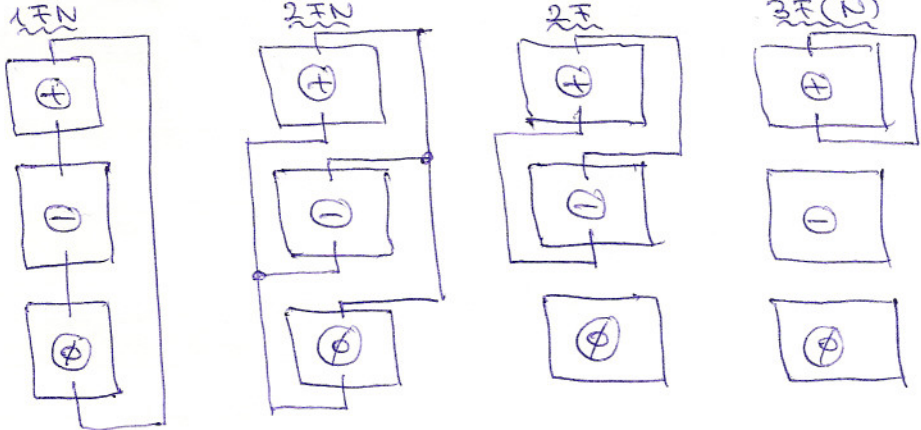
Trafo zékussortrendű helyettesítése:



Foqyasító (Generator zékus sortrendű h.k.-e):



Zárlatok modellezése



Rövid vezeték (feszültségese)

$$I = \frac{S_u}{\sqrt{3} U_n} (\cos \varphi \overset{\text{ind.}}{+} j \sin \varphi) = I_w + j I_m$$

-kap.

$$\Delta U = (U_{s1} - U_{s2}) \approx \Delta U_k = I_w R_v - I_m X_v$$

$$Z_v = R_v + j X_v \quad \Delta U_k = I_w X_v + I_m R_v$$

nagyfesz. (2x30)

$$\Delta U_{U1} = -I_m X_v$$

$$\Delta U_{U2} = I_w X_v$$

$$\Delta U \% = \frac{\Delta U [kV]}{U_n} \cdot 100$$

Rövid vezeték (terhelési szög, teljesítmény)

$$S_{srf} = U_s I^* = P_s + jQ_s$$

$$S_{rfe} = U_r I^* = P_r + jQ_r$$

$$P_s = P_r = \frac{|U_s| \cdot |U_r|}{x} \sin \delta$$

$$Q_s = \frac{|U_s| (|U_s| - |U_r| \cos \delta)}{x}$$

$$Q_r = \frac{|U_r| (|U_s| \cos \delta - |U_r|)}{x}$$

hosszú, megfesz. vezeték (teljesítmény
kördiagramm)

$$U_s = A U_r + B I_r$$

$$S_s = k_s e^{j(\beta - \delta)} - g e^{j(\beta + \theta)}$$

$$I_s = C U_r + D I_r$$

$$S_r = k_r e^{j(\beta - \alpha)} + g e^{j(\beta - \theta)}$$

$$k_s = |U_s|^2 \left| \frac{D}{B} \right| e^{j(\beta - \delta)}$$

$$g = \frac{|U_s| \cdot |U_r|}{|B|}$$

$$k_r = -|U_r|^2 \left| \frac{A}{B} \right| e^{j(\beta - \delta)}$$

rövid vezetékre:

$$|U_s| = |U_r|; |A| = 1; \alpha = \phi; |B| = x_v; \beta = 90^\circ; |D| = 1; \delta = \phi$$

foqyasító értékmegváltozások

$$P = P_0 + P_0 \left(k_{pf} \frac{\Delta f}{f_0} + k_{pu} \frac{\Delta U}{U_0} \right)$$

$$Q = Q_0 + Q_0 \left(k_{qf} \frac{\Delta f}{f_0} + k_{qu} \frac{\Delta U}{U_0} \right)$$